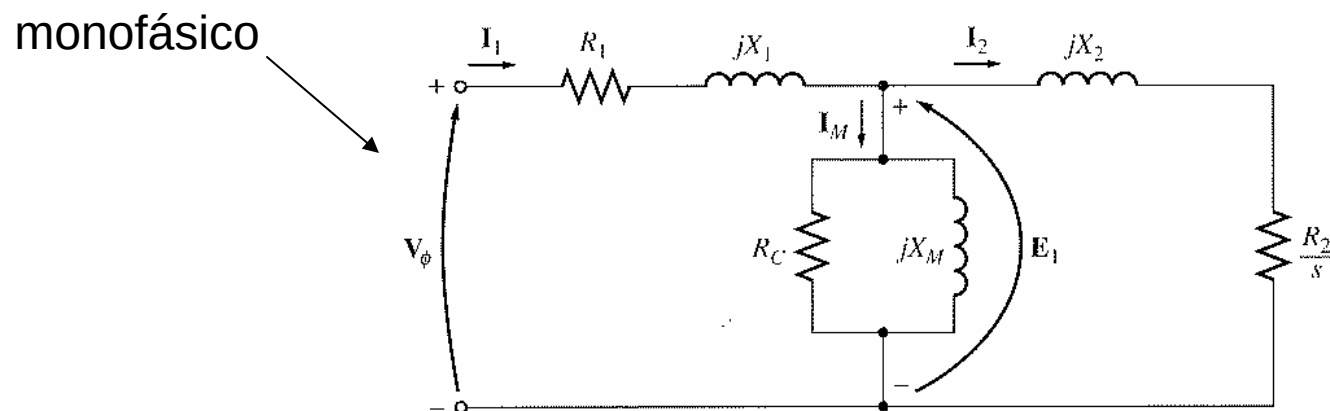
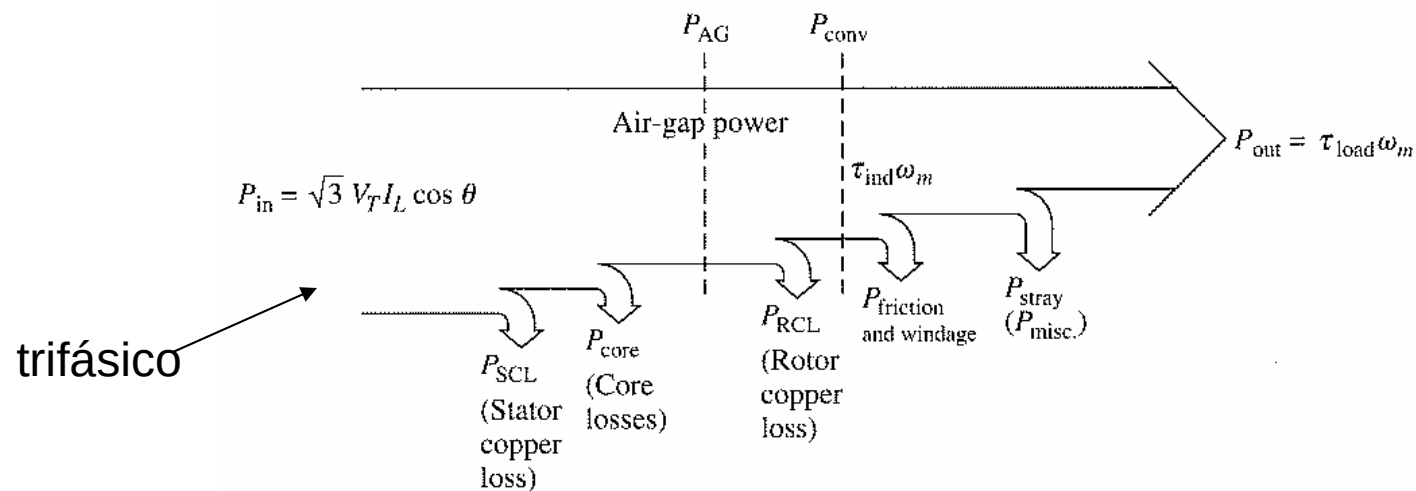


Fundamentos de Transformadores y Máquinas Eléctricas

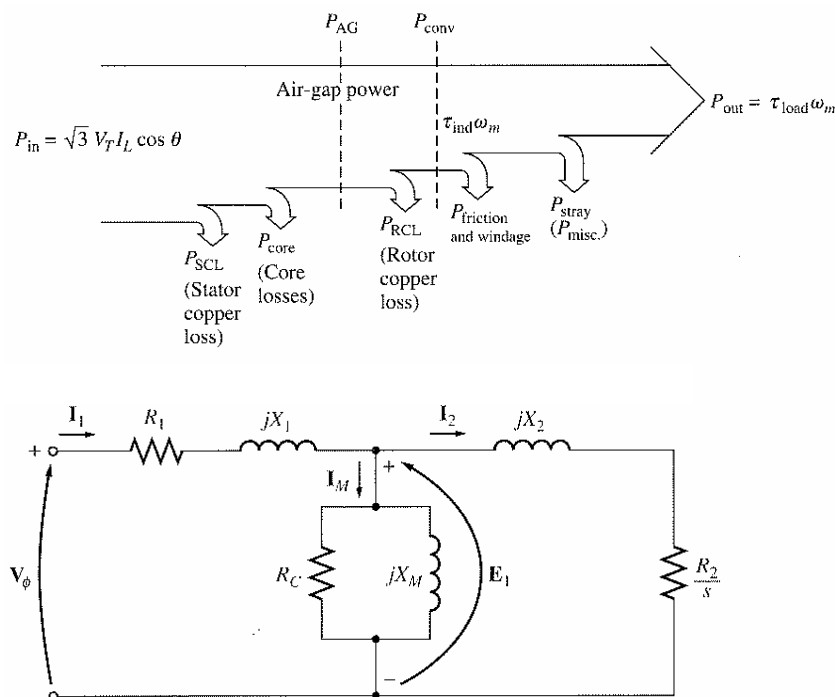
Dr. Lionel R. Orama Exclusa, PE

Clase 14

Potencia y Torque en el IM



Potencia y Torque en el IM

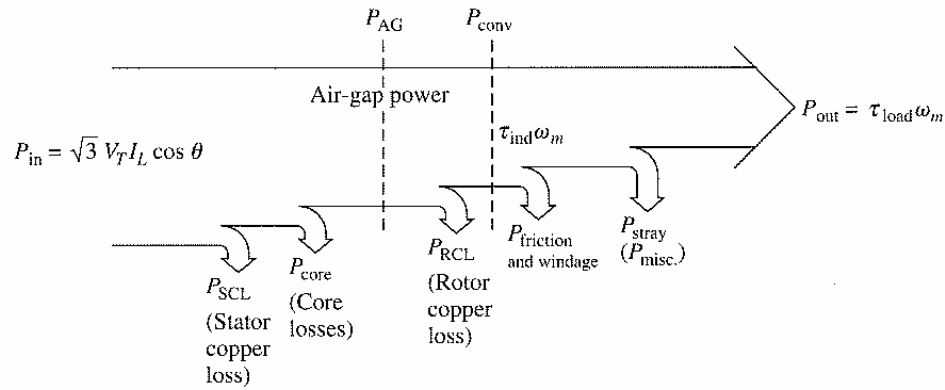


- $P_{in} = \sqrt{3} V_{LL} I_\phi \cos \theta$ Potencia de Entrada
- $P_s = 3 I_s^2 R_s$ Embobinado del estator
- $P_c = 3 E^2 / R_c$ Histeresis y Corrientes Eddie
- $P_{AG} = P_{in} - P_s - P_c$ Transmitida del estator al rotor
- $P_R = 3 I_R^2 R'_R$ Embobinado del rotor
- $P_{conv} = P_{AG} - P_R = \tau_{ind} \omega_r$
- $P_{F\&w} \rightarrow$ Friction and windage (fricción y aire)
- $P_{stray} \rightarrow$ otras pérdidas

Nota: $\rightarrow$ A mayor n_r , mayor $P_{F\&w}$ y P_{stray} , pero menor P_c .

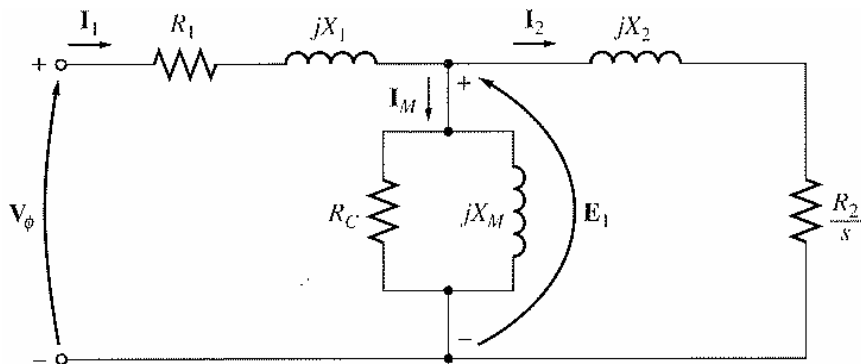
$\rightarrow$ A veces, estas se unen en pérdidas de rotación "Rotational losses" y se consideran constantes.

Ejemplo

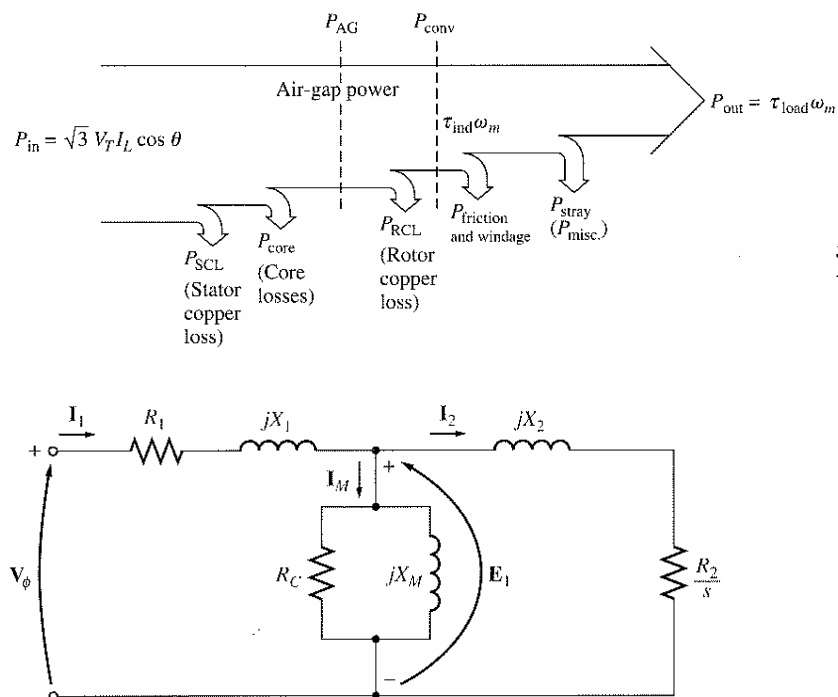


IM: trifásico, 480V, 50hp, 60A, 0.85PF lagging, $P_S=2\text{kW}$, $P_R=0.7\text{kW}$, $P_{F\&W}=0.6\text{kW}$, $P_C=1.8\text{kW}$, P_{STRAY} descartable. Hallar:

- P_{AG}
- P_{CONV}
- P_{OUT}
- Rendimiento



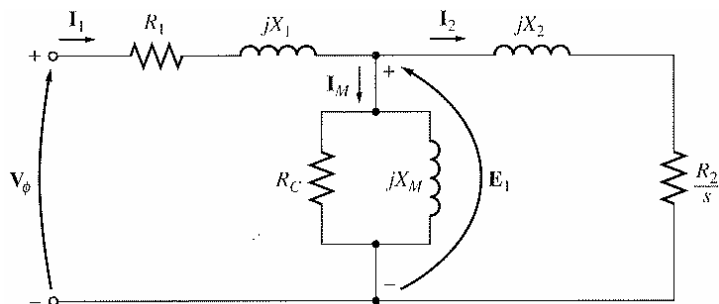
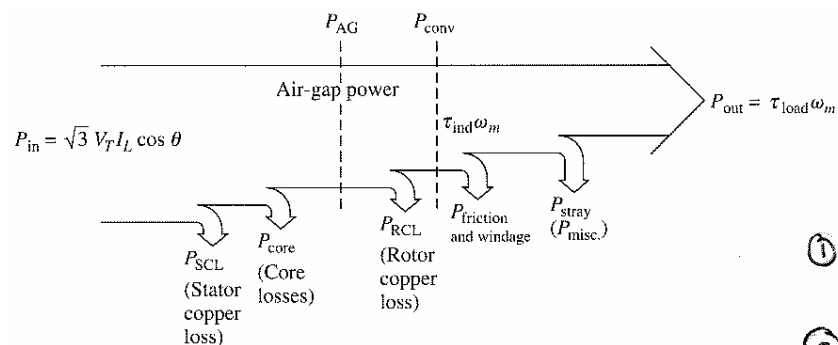
Potencia y Torque en el IM



$$\bar{I}_1 = \bar{I}_s = \frac{\bar{V}_\phi}{\bar{Z}_{eq}}$$

$$\begin{aligned} \bar{Z}_{eq} &= R_s + jX_s + (R_c \parallel jX_m) \parallel \left(\frac{R'_R}{s} + jX'_{BR} \right) \\ &= R_s + jX_s + \frac{1}{\frac{1}{\frac{1}{R_c} + \frac{1}{jX_m}} + \frac{1}{\frac{R'_R}{s} + jX'_{BR}}} \end{aligned}$$

Potencia y Torque en el IM



$$\textcircled{1} \quad P_s = 3 I_1^2 R_s$$

$$\textcircled{2} \quad P_c = 3 \frac{E_1^2}{R_c}$$

$$\textcircled{3} \quad P_{AG} = P_{in} - P_s - P_c$$

$$\textcircled{4} \quad P_{AG} = 3 I_2^2 \frac{R'_R}{s}$$

$$\textcircled{5} \quad P_R = 3 I_2^2 R'_R \quad \left. \begin{array}{l} \\ \end{array} \right\} R'_R = a_{eff}^2 R_R \quad \uparrow \text{embobinado del rotor}$$

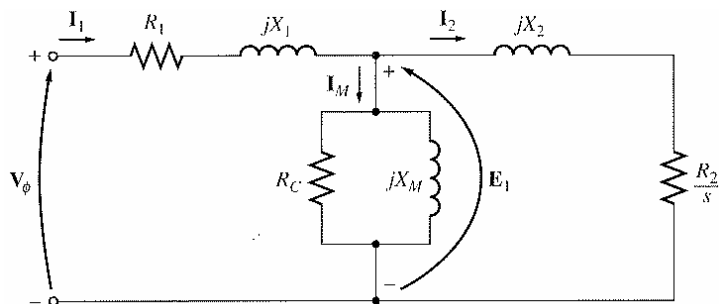
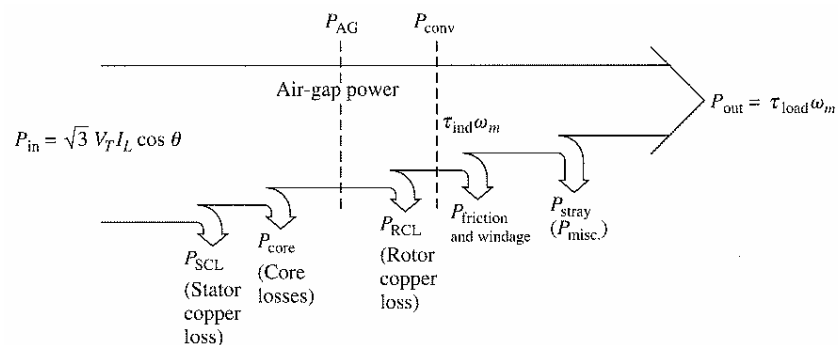
$$P_{conv} = P_{AG} - P_R = 3 I_2^2 R'_R \left(\frac{1}{s} - 1 \right)$$

$$\textcircled{6} \quad P_{conv} = 3 I_2^2 R'_R \left(\frac{1-s}{s} \right)$$

de $\textcircled{4}$ y $\textcircled{5}$

$$\textcircled{7} \quad s P_{AG} = P_R$$

Potencia y Torque en el IM



$$P_{conv} = P_{AG} - P_R \quad ; \quad P_R = s P_{AG}$$

$$P_{conv} = P_{ag} (1 - s)$$

$$P_{out} = P_{conv} - P_{FW} - P_{misc}$$

$$\gamma_{ind} = \frac{P_{conv}}{\omega_R} = \frac{(1-s) P_{AG}}{(1-s) \omega_s}$$

$$\gamma_{ind} = \frac{P_{AG}}{\omega_s}$$

Separando Perdidas en Rotor y P_{conv}

$$R_{\text{conv}} = \frac{R'_R}{s} + R'_R$$

$$R_{\text{conv}} = R'_R \left(\frac{1}{s} - 1 \right) = R'_R \left(\frac{1-s}{s} \right) //$$

